

# $k$ -Sum Hardness Implies $tw$ -SETH

Michael Lampis



GRIF, June 5th 2026

# Main result

# Main result

## Theorem

*If there exists a  $(2 - \varepsilon)^{tw} n^{O(1)}$  time algorithm for 3-SAT  
 $\Rightarrow$  there exists an  $n^{(1-\varepsilon)\frac{k}{2}}$  algorithm for  $k$ -SUM.*

# Main result

## Theorem

*If there exists a  $(2 - \varepsilon)^{tw} n^{O(1)}$  time algorithm for 3-SAT  
 $\Rightarrow$  there exists an  $n^{(1-\varepsilon)\frac{k}{2}}$  algorithm<sup>a</sup> for  $k$ -SUM.*

---

<sup>a</sup>Randomized, for some other  $\varepsilon$  and sufficiently large  $k$

# Main result

## Theorem

*If there exists a  $(2 - \varepsilon)^{tw} n^{O(1)}$  time algorithm for 3-SAT  
 $\Rightarrow$  there exists an  $n^{(1-\varepsilon)\frac{k}{2}}$  algorithm for  $k$ -SUM.*

## Theorem

**(More Informal:)** *If current best algorithm for  $k$ -SUM is **optimal**,  
 $\Rightarrow$  standard DP algorithm for 3-SAT/ $tw$  is also **optimal**.*

# Main result

## Theorem

If there exists a ( )  
⇒ there exists an

## Theorem

(More Informal:  
⇒ standard DP a



Image credit: nano banana

# Main result

## Theorem

*If there exists a  $(2 - \varepsilon)^{tw} n^{O(1)}$  time algorithm for 3-SAT  
 $\Rightarrow$  there exists an  $n^{(1-\varepsilon)\frac{k}{2}}$  algorithm for  $k$ -SUM.*

## Theorem

**(More Informal:)** *If current best algorithm for  $k$ -SUM is **optimal**,  
 $\Rightarrow$  standard DP algorithm for 3-SAT/ $tw$  is also **optimal**.*

- Same statements hold for  $k$ -XOR.
- Result presented in SODA 2026.

# Fair Warning

**WARNING:**  
**Viewer Discretion is Advised.**

# Fair Warning

Talk will be heavy on:

- Controversial Opinions
- **Propaganda**

Objective:

- Build case for research direction
- (**Entertain**)



# Background

# Parameterized Complexity

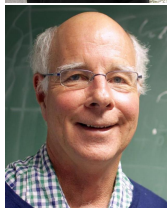
- Do **not** measure complexity as function of input **size**  $n$ .
- Measure complexity as function of input **structure**  $k$ .
- $k$  is the **parameter**.
- Motivating difference:  $f(k)n^{O(1)}$  vs  $n^{g(k)}$ .

Engineer's Motivation:

- If  $f(k)$  is reasonable, this could actually be a useful algorithm!

Scientist's Motivation:

- **Why** are problems hard?



# Parameterized Complexity

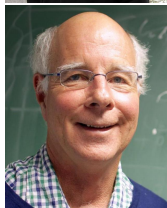
- Do **not** measure complexity as function of input **size**  $n$ .
- Measure complexity as function of input **structure**  $k$ .
- $k$  is the **parameter**.
- Motivating difference:  $f(k)n^{O(1)}$  vs  $n^{g(k)}$ .

Engineer's Motivation:

- If  $f(k)$  is reasonable, this could actually be a useful algorithm!

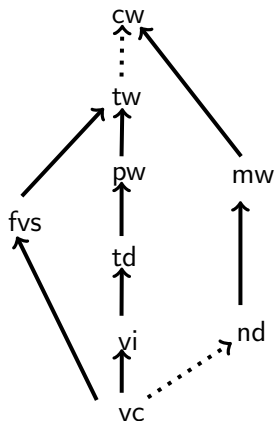
Scientist's Motivation:

- **Why** are problems hard?



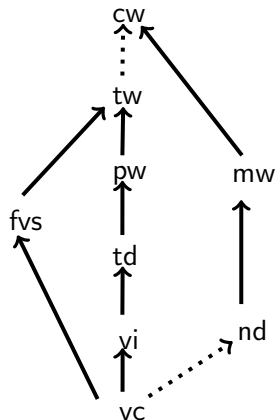
Bottom line: Complexity must take into account **input structure**.

# Which parameters – which structure?



# Which parameters – which structure?

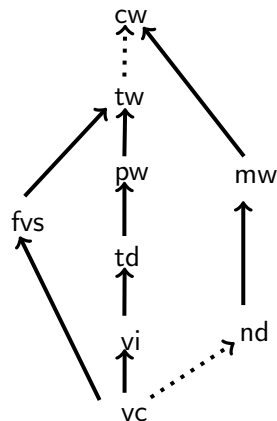
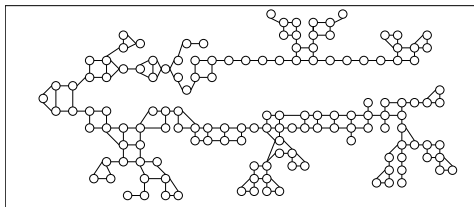
- Key parameter : **Treewidth**
  - ▶  $\text{tw}(G)$  bounded  $\rightarrow G$  is “tree-like”



# Which parameters – which structure?

- Key parameter : **Treewidth**

- ▶  $\text{tw}(G)$  bounded  $\rightarrow G$  is “tree-like”

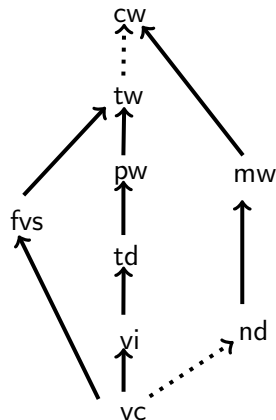
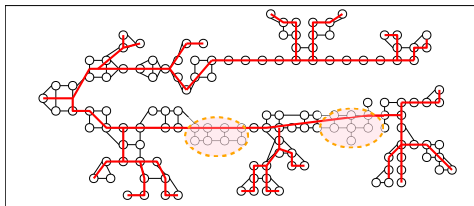




# Which parameters – which structure?

- Key parameter : **Treewidth**

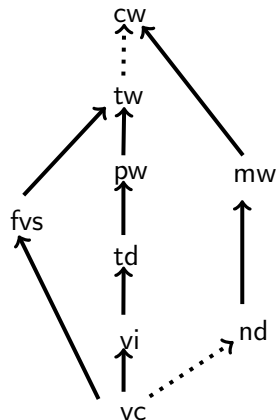
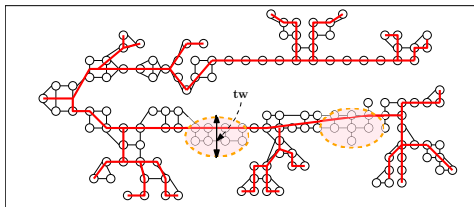
- ▶  $\text{tw}(G)$  bounded  $\rightarrow G$  is “tree-like”



# Which parameters – which structure?

- Key parameter : **Treewidth**

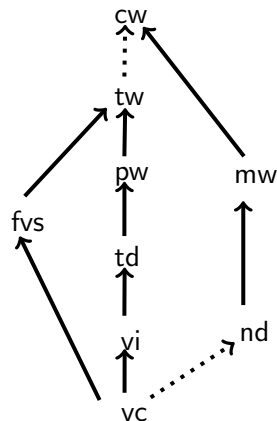
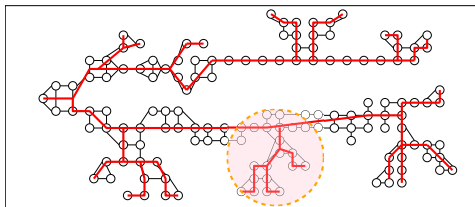
- ▶  $\text{tw}(G)$  bounded  $\rightarrow G$  is “tree-like”



# Which parameters – which structure?

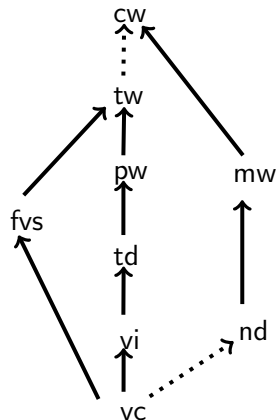
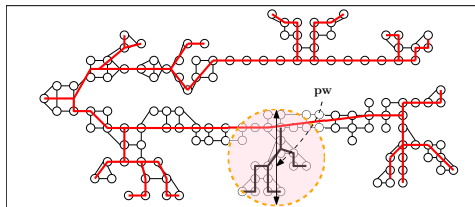
- Key parameter : **Treewidth**

- ▶  $\text{tw}(G)$  bounded  $\rightarrow G$  is “tree-like”



# Which parameters – which structure?

- Key parameter : **Treewidth**
  - ▶  $tw(G)$  bounded  $\rightarrow G$  is “tree-like”



Concretely :

- Pathwidth should be **easier** than treewidth !
  - ▶ For which problems ?
  - ▶ Complexity impact ?  $\rightarrow$  **Fine-Grained complexity**

# Treewidth – Pathwidth

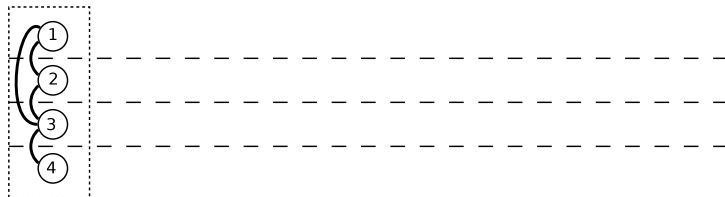
Gentle definition of pathwidth  $k$ :

- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.

# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

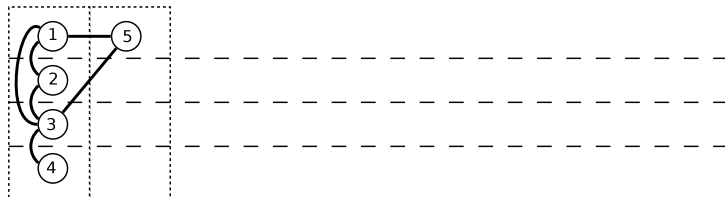
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

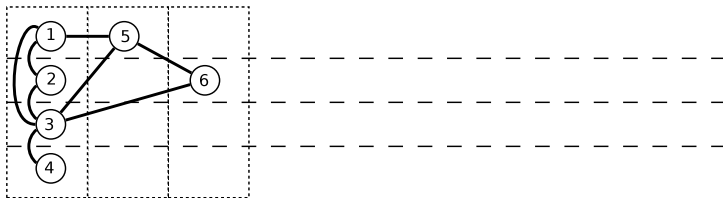
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

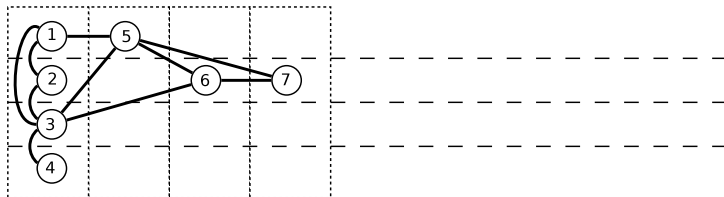
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

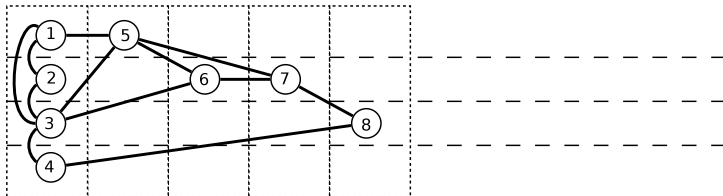
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

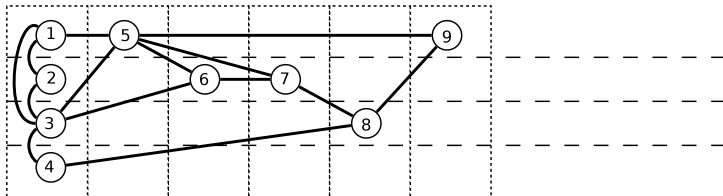
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

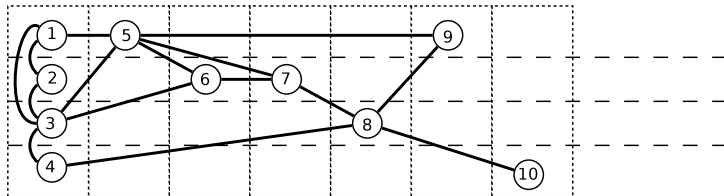
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

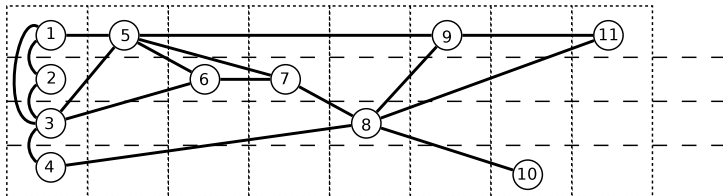
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

Gentle definition of pathwidth  $k$ :

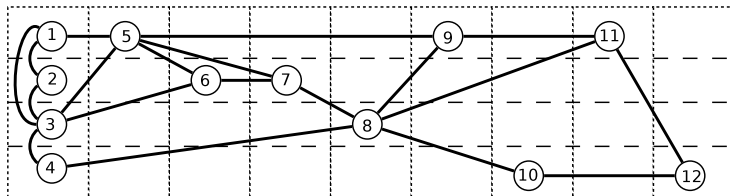
- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



# Treewidth – Pathwidth

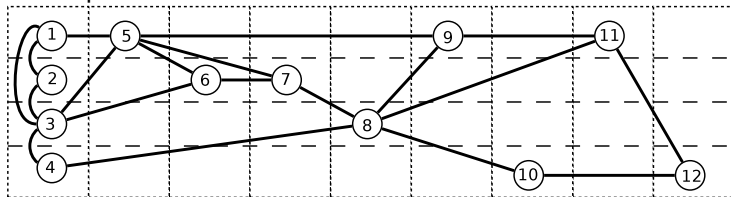
Gentle definition of pathwidth  $k$ :

- We have  $k$  stacks. Initially each contains a vertex. They are arbitrarily connected.
- At each step we add a vertex to the top of a stack. It can be connected to vertices currently on top of a stack.



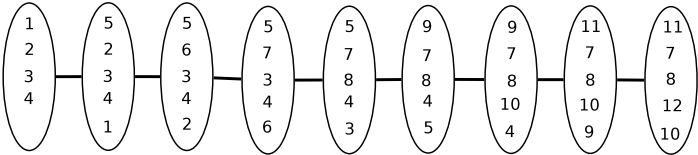
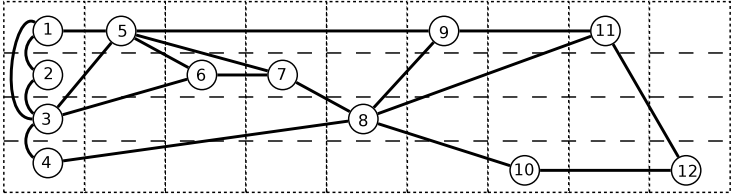
# Treewidth – Pathwidth

Note that this is equivalent to the standard definition of path decompositions.



# Treewidth – Pathwidth

Note that this is equivalent to the standard definition of path decompositions.

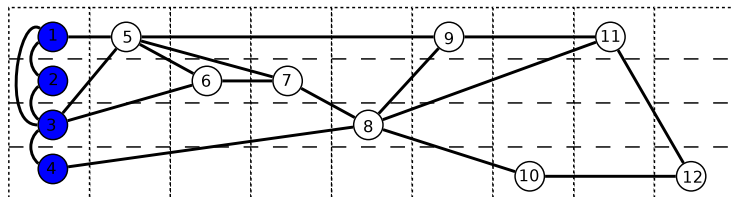


## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.

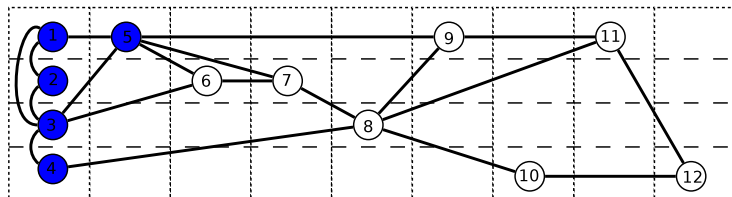
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



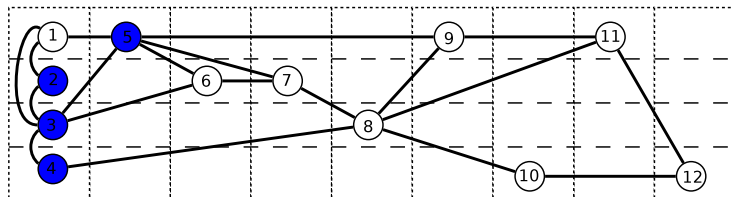
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



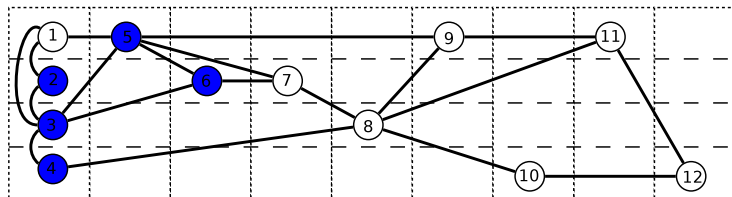
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



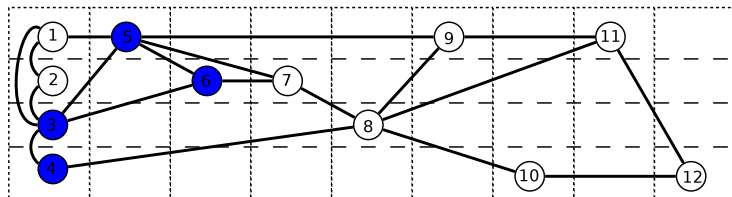
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



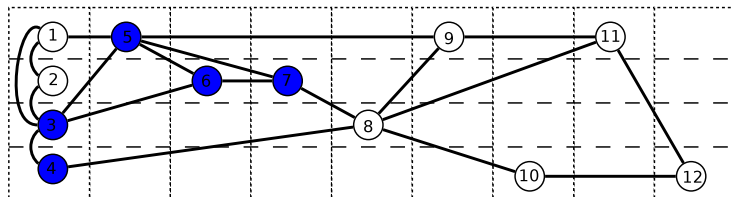
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



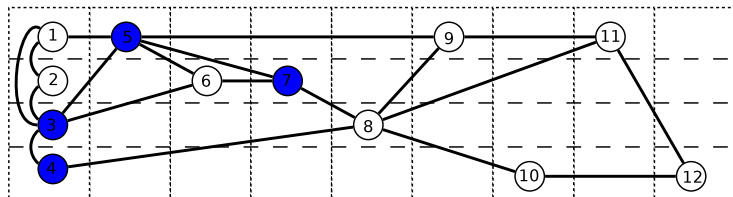
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



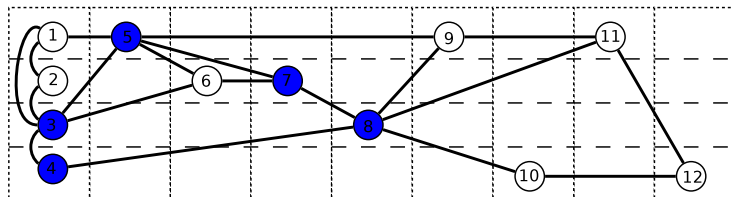
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



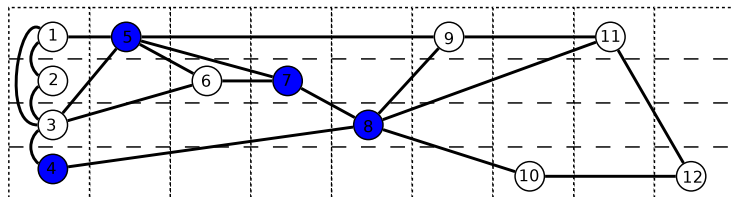
## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.



## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.

For 3-COLORING only need to remember information about boundary

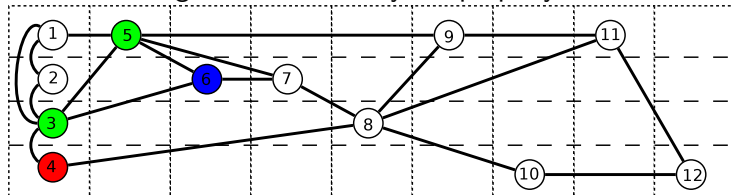
Which colorings of the boundary are properly extendible to the left?

## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.

For 3-COLORING only need to remember information about boundary

Which colorings of the boundary are properly extendible to the left?



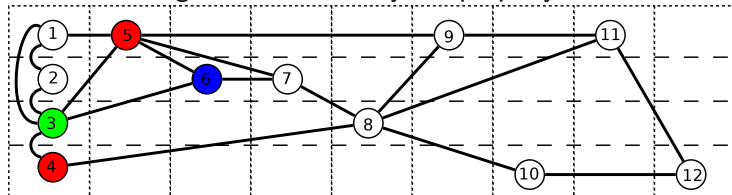
Separator:  $\{3, 4, 5, 6\}$  includes tuple  $(3, 4, 5, 6; \text{No})$  because this coloring does not work

## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.

For 3-COLORING only need to remember information about boundary

Which colorings of the boundary are properly extendible to the left?



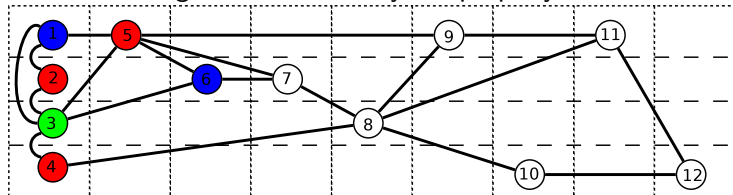
Separator:  $\{3, 4, 5, 6\}$  includes tuple  $(3, 4, 5, 6; \text{Yes})$  because this coloring can be extended to the left

## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.

For 3-COLORING only need to remember information about boundary

Which colorings of the boundary are properly extendible to the left?



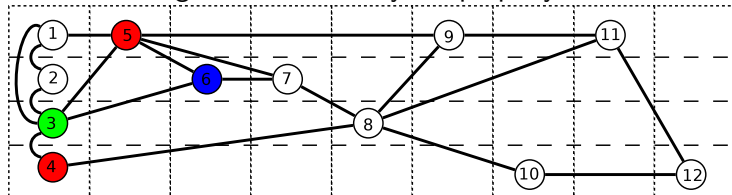
Separator:  $\{3, 4, 5, 6\}$  includes tuple  $(3, 4, 5, 6; \text{Yes})$  because this coloring can be extended to the left

## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.

For 3-COLORING only need to remember information about boundary

Which colorings of the boundary are properly extendible to the left?



We now need to decide which are the good colorings for the separator (3, 4, 5, 7).

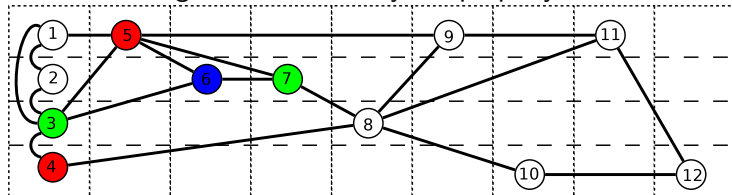
We consider each good coloring of (3, 4, 5, 6).

## Algorithmic view

The reason that tree/path decompositions are useful is that we have a moving boundary of small separators that “sweeps” the graph.

For 3-COLORING only need to remember information about boundary

Which colorings of the boundary are properly extendible to the left?



We now need to decide which are the good colorings for the separator (3, 4, 5, 7).

We consider each good coloring of (3, 4, 5, 6).

We see that (3, 4, 5, 7) is a good coloring.

**Important: we know the colors of all neighbors of 7.**

# Application: Treewidth Lower Bounds

# Application: Treewidth Lower Bounds



Image credit: nano banana (including typo!)

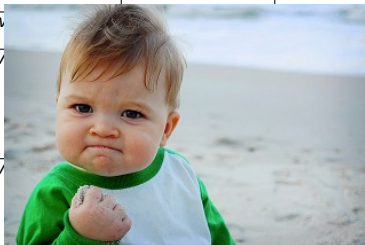
# Application: Treewidth Lower Bounds

|           | Pathwidth            | Treewidth  | Cliquewidth     | Ref   |
|-----------|----------------------|------------|-----------------|---|
| IND SET   | $= 2^w$              | $= 2^w$    | $= 2^w$         | Lokshtanov, Marx, Saurabh<br>TALG'18                            |
| DOM SET   | $= 3^w$              | $= 3^w$    | $= 4^w$         | LMS'18 and Katsikarelis,<br>L., Paschos DAM'19                  |
| $k$ -COL  | $= k^w$              | $= k^w$    | $= (2^k - 2)^w$ | LMS'18 and L. SIDMA'20  |
| MAX CUT   | $= 2^w$              | $= 2^w$    | W[1]-h          | LMS'18 and Fomin,<br>Golovach, Lokshtanov,<br>Saurabh SICOMP'10 |
| CONN VC   | $= 3^w$              | $= 3^w$    | $= 6^w$         | Cygan et al. TALG'22,<br>Hegerfeld, Kratsch<br>ESA'23           |
| HAM CYCLE | $= (2 + \sqrt{2})^w$ | $\leq 4^w$ | W[1]-h          | FGLS'18, Cygan, Kratsch,<br>Nederlof JACM'18                    |

All lower bounds known under SETH.

# Application: Treewidth Lower Bounds

|           | Pathwidth            | Treewidth  | Cliquewidth | Ref   |
|-----------|----------------------|------------|-------------|---|
| IND SET   | $= 2^w$              | $= 2^w$    | $= 2^w$     | Lokshtanov, Marx, Saurabh<br>TALG'18                            |
| DOM SET   | $= 3^w$              | $= 3^w$    | $= 4^w$     | LMS'18 and Katsikarelis,<br>L., Paschos DAM'19                  |
| $k$ -COL  | $= k^w$              |            | $(k-2)^w$   | LMS'18 and L. SIDMA'20  |
| MAX CUT   | $= 2^w$              |            |             | LMS'18 and Fomin,<br>Golovach, Lokshtanov,<br>Saurabh SICOMP'10 |
| CONN VC   | $= 3^w$              |            |             | Cygan et al. TALG'22,<br>Hegerfeld, Kratsch<br>ESA'23           |
| HAM CYCLE | $= (2 + \sqrt{2})^w$ | $\leq 4^w$ | $W[1]$ -h   | FGLS'18, Cygan, Kratsch,<br>Nederlof JACM'18                    |



All lower bounds known under SETH.

## Application: Treewidth Lower Bounds

|           | Pathwidth            | Treewidth  | Cliqueswidth    | Ref   |
|-----------|----------------------|------------|-----------------|---|
| IND SET   | $= 2^w$              | $= 2^w$    | $= 2^w$         | Lokshantov, Marx, Saurabh<br>TALG'18                            |
| DOM SET   | $= 3^w$              | $= 3^w$    | $= 4^w$         | LMS'18 and Katsikarelis,<br>L., Paschos DAM'19                  |
| $k$ -COL  | $= k^w$              | $= k^w$    | $= (2^k - 2)^w$ | LMS'18 and L. SIDMA'20  |
| MAX CUT   | $= 2^w$              | $= 2^w$    | W[1]-h          | LMS'18 and Fomin,<br>Golovach, Lokshantov,<br>Saurabh SICOMP'10 |
| CONN VC   | $= 3^w$              | $= 3^w$    | $= 6^w$         | Cygan et al. TALG'22,<br>Hegerfeld, Kratsch<br>ESA'23           |
| HAM CYCLE | $= (2 + \sqrt{2})^w$ | $\leq 4^w$ | W[1]-h          | FGLS'18, Cygan, Kratsch,<br>Nederlof JACM'18                    |

All lower bounds known under **SETH**.

# Motivation and Context

# Motivation and Context



Image credit: nano banana (including typo!)

# Motivation and Context

- Many different **flavors** of complexity hypotheses
  - ▶ SETH:  $k$ -SAT needs brute-force
  - ▶ Set Cover Conjecture (SCC): SET COVER needs brute-force DP
  - ▶  $k$ -SUM/3-SUM: Meet in the middle is **optimal**
- Some more **credible** than others(?)
  - ▶ But typically few implications/relations known
- Some more **relevant** than others
  - ▶ SETH (and SCC) **main** hypotheses for **Parameterized Complexity**

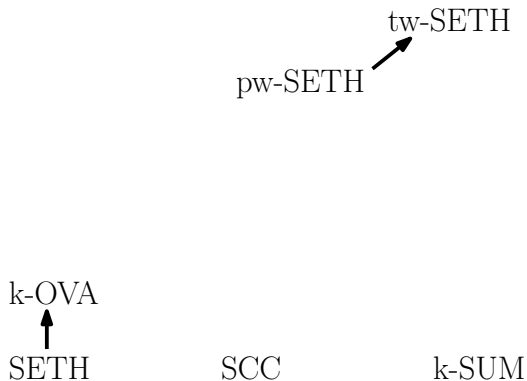
# Hypotheses

k-OVA  
↑  
SETH

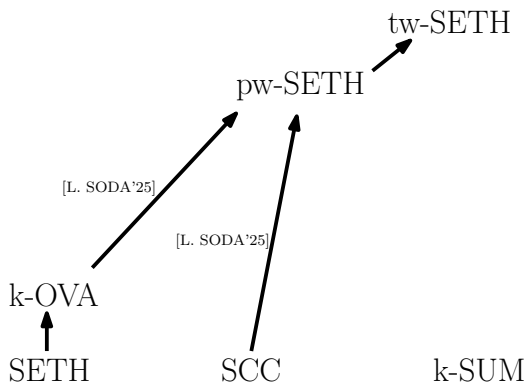
SCC

k-SUM

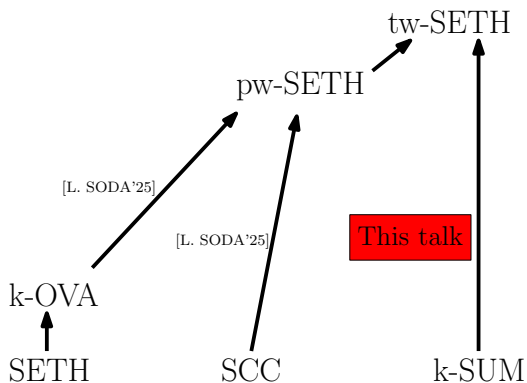
# Hypotheses



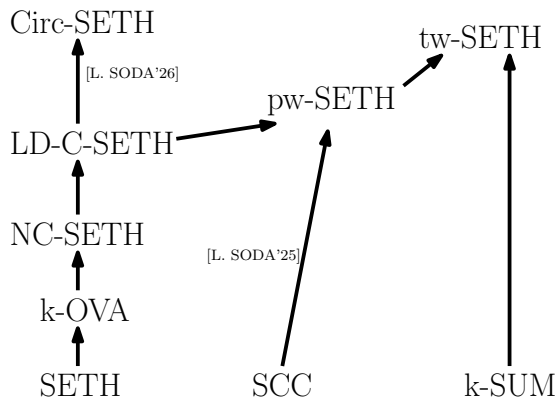
# Hypotheses



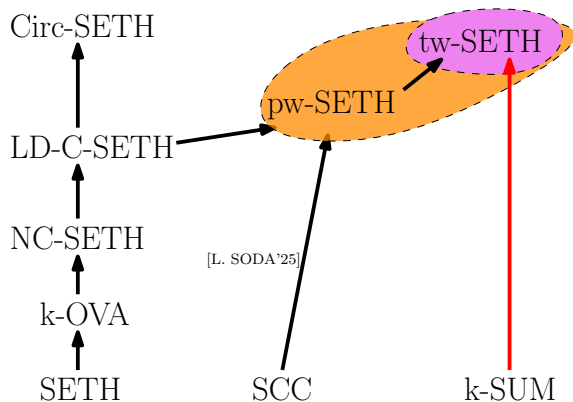
# Hypotheses



# Hypotheses



# Hypotheses



# Proof Sketch

# Setup

## Definition

In  $k$ -SUM, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$  integers each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\sum_j A_j[i_j] = 0$ .

# Setup

## Definition

In  $k$ -SUM, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$  integers each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\sum_j A_j[i_j] = 0$ .

| $A_1$     | $A_2$     | $A_3$     | $A_4$     | $A_5$     | $A_6$     |
|-----------|-----------|-----------|-----------|-----------|-----------|
| $x_{1,1}$ | $x_{2,1}$ | $x_{3,1}$ | $x_{4,1}$ | $x_{5,1}$ | $x_{6,1}$ |
| $x_{1,2}$ | $x_{2,2}$ | $x_{3,2}$ | $x_{4,2}$ | $x_{5,2}$ | $x_{6,2}$ |
| $x_{1,3}$ | $x_{2,3}$ | $x_{3,3}$ | $x_{4,3}$ | $x_{5,3}$ | $x_{6,3}$ |
| $x_{1,4}$ | $x_{2,4}$ | $x_{3,4}$ | $x_{4,4}$ | $x_{5,4}$ | $x_{6,4}$ |
| $x_{1,5}$ | $x_{2,5}$ | $x_{3,5}$ | $x_{4,5}$ | $x_{5,5}$ | $x_{6,5}$ |
| $x_{1,6}$ | $x_{2,6}$ | $x_{3,6}$ | $x_{4,6}$ | $x_{5,6}$ | $x_{6,6}$ |
| $x_{1,7}$ | $x_{2,7}$ | $x_{3,7}$ | $x_{4,7}$ | $x_{5,7}$ | $x_{6,7}$ |
| $x_{1,8}$ | $x_{2,8}$ | $x_{3,8}$ | $x_{4,8}$ | $x_{5,8}$ | $x_{6,8}$ |

# Setup

## Definition

In  $k$ -SUM, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$  integers each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\sum_j A_j[i_j] = 0$ .

| $A_1$     | $A_2$     | $A_3$     | $A_4$     | $A_5$     | $A_6$     |
|-----------|-----------|-----------|-----------|-----------|-----------|
| $x_{1,1}$ | $x_{2,1}$ | $x_{3,1}$ | $x_{4,1}$ | $x_{5,1}$ | $x_{6,1}$ |
| $x_{1,2}$ | $x_{2,2}$ | $x_{3,2}$ | $x_{4,2}$ | $x_{5,2}$ | $x_{6,2}$ |
| $x_{1,3}$ | $x_{2,3}$ | $x_{3,3}$ | $x_{4,3}$ | $x_{5,3}$ | $x_{6,3}$ |
| $x_{1,4}$ | $x_{2,4}$ | $x_{3,4}$ | $x_{4,4}$ | $x_{5,4}$ | $x_{6,4}$ |
| $x_{1,5}$ | $x_{2,5}$ | $x_{3,5}$ | $x_{4,5}$ | $x_{5,5}$ | $x_{6,5}$ |
| $x_{1,6}$ | $x_{2,6}$ | $x_{3,6}$ | $x_{4,6}$ | $x_{5,6}$ | $x_{6,6}$ |
| $x_{1,7}$ | $x_{2,7}$ | $x_{3,7}$ | $x_{4,7}$ | $x_{5,7}$ | $x_{6,7}$ |
| $x_{1,8}$ | $x_{2,8}$ | $x_{3,8}$ | $x_{4,8}$ | $x_{5,8}$ | $x_{6,8}$ |

Sum = 0?

# Setup

## Definition

In  $k$ -SUM, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$  integers each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\sum_j A_j[i_j] = 0$ .

High-level strategy:

- Reduce the given instance to a SAT formula of small treewidth
- Show that fast algorithm for such formulas  $\Rightarrow$  fast algorithm for  $k$ -SUM.

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$   $d$ -bit vectors each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\prod_j A_j[i_j] = 0$ .

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$   $d$ -bit vectors each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\prod_j A_j[i_j] = 0$ .

| $A_1$     | $A_2$     | $A_3$     | $A_4$     | $A_5$     | $A_6$     |
|-----------|-----------|-----------|-----------|-----------|-----------|
| $x_{1,1}$ | $x_{2,1}$ | $x_{3,1}$ | $x_{4,1}$ | $x_{5,1}$ | $x_{6,1}$ |
| $x_{1,2}$ | $x_{2,2}$ | $x_{3,2}$ | $x_{4,2}$ | $x_{5,2}$ | $x_{6,2}$ |
| $x_{1,3}$ | $x_{2,3}$ | $x_{3,3}$ | $x_{4,3}$ | $x_{5,3}$ | $x_{6,3}$ |
| $x_{1,4}$ | $x_{2,4}$ | $x_{3,4}$ | $x_{4,4}$ | $x_{5,4}$ | $x_{6,4}$ |
| $x_{1,5}$ | $x_{2,5}$ | $x_{3,5}$ | $x_{4,5}$ | $x_{5,5}$ | $x_{6,5}$ |
| $x_{1,6}$ | $x_{2,6}$ | $x_{3,6}$ | $x_{4,6}$ | $x_{5,6}$ | $x_{6,6}$ |
| $x_{1,7}$ | $x_{2,7}$ | $x_{3,7}$ | $x_{4,7}$ | $x_{5,7}$ | $x_{6,7}$ |
| $x_{1,8}$ | $x_{2,8}$ | $x_{3,8}$ | $x_{4,8}$ | $x_{5,8}$ | $x_{6,8}$ |

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$   $d$ -bit vectors each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\prod_j A_j[i_j] = 0$ .

| $A_1$     | $A_2$     | $A_3$     | $A_4$     | $A_5$     | $A_6$     |
|-----------|-----------|-----------|-----------|-----------|-----------|
| $x_{1,1}$ | $x_{2,1}$ | $x_{3,1}$ | $x_{4,1}$ | $x_{5,1}$ | $x_{6,1}$ |
| $x_{1,2}$ | $x_{2,2}$ | $x_{3,2}$ | $x_{4,2}$ | $x_{5,2}$ | $x_{6,2}$ |
| $x_{1,3}$ | $x_{2,3}$ | $x_{3,3}$ | $x_{4,3}$ | $x_{5,3}$ | $x_{6,3}$ |
| $x_{1,4}$ | $x_{2,4}$ | $x_{3,4}$ | $x_{4,4}$ | $x_{5,4}$ | $x_{6,4}$ |
| $x_{1,5}$ | $x_{2,5}$ | $x_{3,5}$ | $x_{4,5}$ | $x_{5,5}$ | $x_{6,5}$ |
| $x_{1,6}$ | $x_{2,6}$ | $x_{3,6}$ | $x_{4,6}$ | $x_{5,6}$ | $x_{6,6}$ |
| $x_{1,7}$ | $x_{2,7}$ | $x_{3,7}$ | $x_{4,7}$ | $x_{5,7}$ | $x_{6,7}$ |
| $x_{1,8}$ | $x_{2,8}$ | $x_{3,8}$ | $x_{4,8}$ | $x_{5,8}$ | $x_{6,8}$ |

Product = 0?

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$   $d$ -bit vectors each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\prod_j A_j[i_j] = 0$ .

Looks similar?



Image credit: nano banana

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$   $d$ -bit vectors each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\prod_j A_j[i_j] = 0$ .

- Construct a SAT formula with  $k \log n$  **main** variables.
- Each group of  $\log n$  variables encodes a different  $i_j$ .
- Add  $d$  groups of vars/clauses to check that each bit of the result is 0.

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$   $d$ -bit vectors each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\prod_j A_j[i_j] = 0$ .

- Construct a SAT formula with  $k \log n$  **main** variables.
- Each group of  $\log n$  variables encodes a different  $i_j$ .
- Add  $d$  groups of vars/clauses to check that each bit of the result is 0.
- Pathwidth is (essentially)  $k \log n$
- $(2 - \varepsilon)^{\text{pw}} n^{O(1)}$  algorithm for SAT  $\Rightarrow n^{(1-\varepsilon)k}$  algorithm for  $k$ -OV

[L. SODA'25]

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given  $k$  arrays  $A_1, \dots, A_k$  of  $n$   $d$ -bit vectors each and are asked if it is possible to select  $i_1, \dots, i_k \in [n]$  such that  $\prod_j A_j[i_j] = 0$ .

- Construct a SAT formula with  $k \log n$  **main** variables.
- Each group of  $\log n$  variables encodes a different  $i_j$ .
- Add  $d$  groups of vars/clauses to check that each bit of the result is 0.
- Pathwidth is (essentially)  $k \log n$
- $(2 - \varepsilon)^{\text{pw}} n^{O(1)}$  algorithm for SAT  $\Rightarrow n^{(1-\varepsilon)k}$  algorithm for  $k$ -OV  
[L. SODA'25]
- Great! Why don't we do the same for  $k$ -SUM?

# Past success is not a guarantee

## Definition

In  $k$ -OV, we are given a matrix  $A$  with entries  $A_{ij} \in \{-1, 1\}$ . We are asked if it is possible to choose a vector  $x$  such that  $\sum_{j=1}^n A_{ij} x_j = 0$  for all  $i$ .

- Construct a reduction from  $k$ -SAT to  $k$ -OV.
- Each group of  $k$  literals in a clause is a vector.
- Add  $d$  groups of  $k$  literals to each clause.
- Pathwidth  $\leq k$ .
- $(2 - \epsilon)^{PW} n$  clauses.
- [L. SODA'25]
- Great! What about the next step?



...ors each and are  
 $\sum_{j=1}^n A_{ij} x_j = 0$ .

s.

of the result is 0.

...m for  $k$ -OV

# Meet in the middle

# Meet in the middle

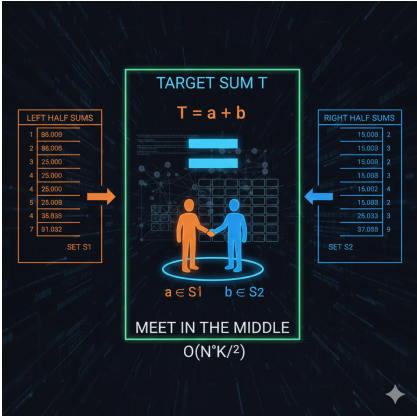


Image credit: nano banana (including nonsensical math)

# Meet in the middle

| $A_1$     | $A_2$     | $A_3$     | $A_4$     | $A_5$     | $A_6$     |
|-----------|-----------|-----------|-----------|-----------|-----------|
| $x_{1,1}$ | $x_{2,1}$ | $x_{3,1}$ | $x_{4,1}$ | $x_{5,1}$ | $x_{6,1}$ |
| $x_{1,2}$ | $x_{2,2}$ | $x_{3,2}$ | $x_{4,2}$ | $x_{5,2}$ | $x_{6,2}$ |
| $x_{1,3}$ | $x_{2,3}$ | $x_{3,3}$ | $x_{4,3}$ | $x_{5,3}$ | $x_{6,3}$ |
| $x_{1,4}$ | $x_{2,4}$ | $x_{3,4}$ | $x_{4,4}$ | $x_{5,4}$ | $x_{6,4}$ |
| $x_{1,5}$ | $x_{2,5}$ | $x_{3,5}$ | $x_{4,5}$ | $x_{5,5}$ | $x_{6,5}$ |
| $x_{1,6}$ | $x_{2,6}$ | $x_{3,6}$ | $x_{4,6}$ | $x_{5,6}$ | $x_{6,6}$ |
| $x_{1,7}$ | $x_{2,7}$ | $x_{3,7}$ | $x_{4,7}$ | $x_{5,7}$ | $x_{6,7}$ |
| $x_{1,8}$ | $x_{2,8}$ | $x_{3,8}$ | $x_{4,8}$ | $x_{5,8}$ | $x_{6,8}$ |

# Meet in the middle

| $A_1$     | $A_2$     | $A_3$     | $A_4$     | $A_5$     | $A_6$     |
|-----------|-----------|-----------|-----------|-----------|-----------|
| $x_{1,1}$ | $x_{2,1}$ | $x_{3,1}$ | $x_{4,1}$ | $x_{5,1}$ | $x_{6,1}$ |
| $x_{1,2}$ | $x_{2,2}$ | $x_{3,2}$ | $x_{4,2}$ | $x_{5,2}$ | $x_{6,2}$ |
| $x_{1,3}$ | $x_{2,3}$ | $x_{3,3}$ | $x_{4,3}$ | $x_{5,3}$ | $x_{6,3}$ |
| $x_{1,4}$ | $x_{2,4}$ | $x_{3,4}$ | $x_{4,4}$ | $x_{5,4}$ | $x_{6,4}$ |
| $x_{1,5}$ | $x_{2,5}$ | $x_{3,5}$ | $x_{4,5}$ | $x_{5,5}$ | $x_{6,5}$ |
| $x_{1,6}$ | $x_{2,6}$ | $x_{3,6}$ | $x_{4,6}$ | $x_{5,6}$ | $x_{6,6}$ |
| $x_{1,7}$ | $x_{2,7}$ | $x_{3,7}$ | $x_{4,7}$ | $x_{5,7}$ | $x_{6,7}$ |
| $x_{1,8}$ | $x_{2,8}$ | $x_{3,8}$ | $x_{4,8}$ | $x_{5,8}$ | $x_{6,8}$ |

# Meet in the middle

| $A_1$     | $A_2$     | $A_3$     |
|-----------|-----------|-----------|
| $x_{1,1}$ | $x_{2,1}$ | $x_{3,1}$ |
| $x_{1,2}$ | $x_{2,2}$ | $x_{3,2}$ |
| $x_{1,3}$ | $x_{2,3}$ | $x_{3,3}$ |
| $x_{1,4}$ | $x_{2,4}$ | $x_{3,4}$ |
| $x_{1,5}$ | $x_{2,5}$ | $x_{3,5}$ |
| $x_{1,6}$ | $x_{2,6}$ | $x_{3,6}$ |
| $x_{1,7}$ | $x_{2,7}$ | $x_{3,7}$ |
| $x_{1,8}$ | $x_{2,8}$ | $x_{3,8}$ |

| $A_4$     | $A_5$     | $A_6$     |
|-----------|-----------|-----------|
| $x_{4,1}$ | $x_{5,1}$ | $x_{6,1}$ |
| $x_{4,2}$ | $x_{5,2}$ | $x_{6,2}$ |
| $x_{4,3}$ | $x_{5,3}$ | $x_{6,3}$ |
| $x_{4,4}$ | $x_{5,4}$ | $x_{6,4}$ |
| $x_{4,5}$ | $x_{5,5}$ | $x_{6,5}$ |
| $x_{4,6}$ | $x_{5,6}$ | $x_{6,6}$ |
| $x_{4,7}$ | $x_{5,7}$ | $x_{6,7}$ |
| $x_{4,8}$ | $x_{5,8}$ | $x_{6,8}$ |

# Meet in the middle

Algorithm:

- Construct two **large** arrays (size  $n^{k/2}$ ):
  - ▶  $L$  has all sums constructible from  $A_1, \dots, A_{k/2}$
  - ▶  $R$  has all sums constructible from  $A_{k/2+1}, \dots, A_k$
- Check if exists  $x \in L, y \in R$  such that  $x + y = 0$ 
  - ▶ Equivalently: check if  $L \cap R \neq \emptyset$
- Can be done in time  $\tilde{O}(n^{k/2})$ .

# Meet in the middle

Algorithm:

- Construct two **large** arrays (size  $n^{k/2}$ ):
  - ▶  $L$  has all sums constructible from  $A_1, \dots, A_{k/2}$
  - ▶  $R$  has all sums constructible from  $A_{k/2+1}, \dots, A_k$
- Check if exists  $x \in L, y \in R$  such that  $x + y = 0$ 
  - ▶ Equivalently: check if  $L \cap R \neq \emptyset$
- Can be done in time  $\tilde{O}(n^{k/2})$ .
  
- **Consequence:** we need a reduction to SAT which produces a formula of width  $\frac{k}{2} \log n$  (**not**  $k \log n$ )
- Running standard DP on this formula should be **as fast as** meet-in-the middle
  - ▶ Otherwise, a small improvement on the SAT algorithm will not beat meet-in-the-middle. . .

# Machines and intuition

## Machine Characterizations of $p_w$ -SETH and $tw$ -SETH

- $p_w$ -SETH: Non-deterministic TM with space  $p_w + O(\log n)$  [Iwata Yoshida ESA'15]
- $tw$ -SETH: Alternating TM with space  $p_w + O(\log n)$  and  $O(\log n)$  alternations

# Machines and intuition

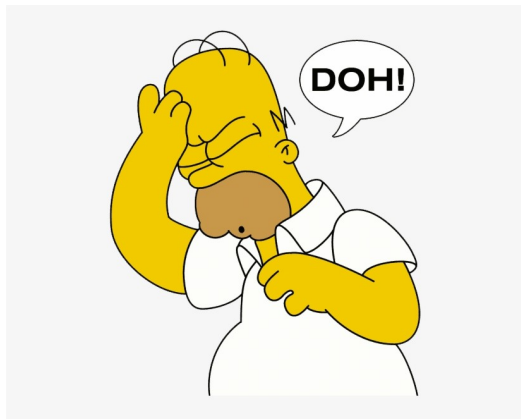
## Machine Characterizations of $\text{pw-SETH}$ and $\text{tw-SETH}$

- $\text{pw-SETH}$ : Non-deterministic TM with space  $\text{pw} + O(\log n)$  [Iwata Yoshida ESA'15]
- $\text{tw-SETH}$ : Alternating TM with space  $\text{pw} + O(\log n)$  and  $O(\log n)$  alternations

Is  $k\text{-SUM}$  in NL?

- Yes, but needs space  $k \log n \dots$

# Machines and intuition



and  $\text{tw-SETH}$

$n$  space  $\text{pw} + O(\log n)$  [Iwata

:  $\text{pw} + O(\log n)$  and  $O(\log n)$

# Low Space NDTM for $k$ -SUM

How little memory can an NDTM use to solve  $k$ -SUM?

- Approach 1: guess solution indices, then verify
  - ▶ Need  $k \log n$  bits to store solution. . .

# Low Space NDTM for $k$ -SUM

How little memory can an NDTM use to solve  $k$ -SUM?

- Approach 1: guess solution indices, then verify
  - ▶ Need  $k \log n$  bits to store solution. . .
- Approach 2: keep track of current sum, for each element non-deterministically check whether to take it.
  - ▶ Space needed:  $\log W + O(\log n)$ , where  $W$  is max absolute value
  - ▶ Is this better??

# Hash me if you can!

Strategy:

- Find a hash function  $h : \mathbb{N} \rightarrow \{-W, \dots, W\}$  such that
  - ▶  $h$  is (almost-)linear:  $h(x + y) \approx h(x) + h(y)$
  - ▶  $h$  is “random-looking”
  - ▶  $W$  is **small** (ideally  $n^{k/2}$ )

# Hash me if you can!

## Strategy:

- Find a hash function  $h : \mathbb{N} \rightarrow \{-W, \dots, W\}$  such that
  - ▶  $h$  is (almost-)linear:  $h(x + y) \approx h(x) + h(y)$
  - ▶  $h$  is “random-looking”
  - ▶  $W$  is **small** (ideally  $n^{k/2}$ )
- Almost-linearity guarantees no false negatives
- Good hash function  $\Rightarrow$  no false positives
- NDTM needs  $\log W + O(\log n) = \frac{k}{2} \log n + O(\log n)$  space
- **Therefore:**  $k$ -SUM  $\Rightarrow$  pw-SETH

Hash me if you can!



such that

$O(\log n)$  space

**Doesn't work!**

# How much can you hash?

What is the smallest viable value of  $W$ ?

- Recall  $L \cup R$  has size  $O(n^{k/2})$
- We need to hash preserving the answer to  $L \cap R \neq \emptyset$ ?
- There are  $|L| \times |R|$  possible **bad** pairs

# How much can you hash?

What is the smallest viable value of  $W$ ?

- Recall  $L \cup R$  has size  $O(n^{k/2})$
- We need to hash preserving the answer to  $L \cap R \neq \emptyset$ ?
- There are  $|L| \times |R|$  possible **bad** pairs
- If we set  $W > n^k$  (and  $h$  is “random”) whp no pair collides
- However, if  $W < n^k$ , we will get false positives whp!!

# How much can you hash?

What is the smallest viable value of  $W$ ?

- Recall  $L \cup R$  has size  $O(n)$
- We need to hash pres  $L \cap R \neq \emptyset$ ?
- There are  $|L| \times |R|$  possible pairs
- If we set  $W > n^k$  (where  $k$  is the number of bits in the hash), then a pair collides
- However, if  $W < n^k$  then a pair collides with probability  $1 - \frac{W}{n^k}$ !



## Birthday Paradox!

# Perfect Hashing with Arthur and Merlin

# Perfect Hashing with Arthur and Merlin



Image credit: ChatGPT

# Perfect Hashing with Arthur and Merlin

Perfect Hashing:

- Can I hash  $N$  items into a range of size  $O(N)$  without collisions?
  - ▶ In one shot, **No**, because of birthday paradox problem we saw
  - ▶ In two steps, **Yes!**
    - ★ (Fredman, Komlós, Szemerédi J.ACM'84)
  - ▶ Key intuition: run through a first hash function, each bucket will have few collisions, run through a second hash function to sort them out.

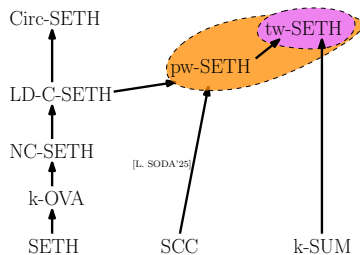
# Perfect Hashing with Arthur and Merlin

Protocol:

- Apply an almost-linear hash  $h : \mathbb{N} \rightarrow \{-W, \dots, W\}$ , with  $W = n^{k/2}$ 
  - ▶ Will almost surely have **false positives**
- Challenge the prover to give  $x \in L, y \in R$  with  $h(x) = h(y)$ 
  - ▶ Prover **commits** to  $h(x) = h(y)$ , which we **store in memory**
- Pick a second hash function  $h' : \mathbb{N} \rightarrow \{-w, \dots, w\}$ , where  $w$  is large enough to perfectly hash **a single bucket**
- Challenge prover to give  $x \in L, y \in R$  with
  - ▶  $h(x) = h(y)$  as before
  - ▶  $h'(x) = h'(y)$
- **Key Intuition:** Treewidth  $\Leftrightarrow$  Alternating TM  $\Leftrightarrow$  Interactive Proof

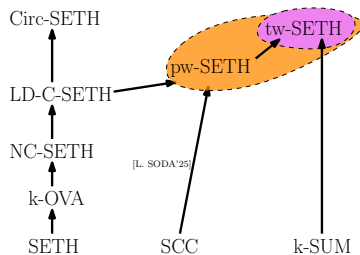
# Open Questions

# Open Questions



- $k\text{-SUM} \Rightarrow \text{pw-SETH}$ ?
- Other connections?

# Open Questions



- $k\text{-SUM} \Rightarrow \text{pw-SETH}$ ?
- Other connections?

Thank you!