

# On Minimum Connecting Transition Sets in Graphs

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## 1 Context

- Forbidden transitions
- Connecting transition sets

## 2 Our results

- Upper bounds
- Reformulation
- Main results

# Motivation

We use **graphs** to model networks in various fields of application (road networks, telecommunication networks, public transit...).

Set of possible walks in a road network  
 $\neq$  set of walks in the graph.

**We need a stronger model !**



# Forbidden-transition graphs

- **Transition** : pair of adjacent distinct edges.
- **Forbidden-transition graph** :  $G = (V, E, T)$  where  $T$  is the set of permitted transitions.
- The walk  $W = (v_1, v_2, \dots, v_k)$  **uses** the transition  $v_i v_{i+1} v_{i+2}$  for all  $i$  such that  $v_i \neq v_{i+2}$ .
- The walk  $W$  is  **$T$ -compatible** if and only if it only uses transitions from  $T$ .

# Related works

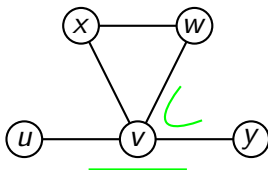
- Properly-coloured walks in edge-coloured graphs.
- Antidirected walks in digraphs.
- Forbidden subpaths / subwalks.

# $T$ -connectivity

## $T$ -connectivity

A graph  $G = (V, E)$  is  $T$ -connected if and only if there exists a  $T$ -compatible walk between each pair of vertices.

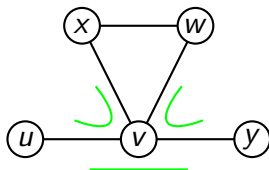
In this case, we say that  $T$  is a connecting transition set of  $G$ .



$$T_1 = \{uvy, wvy\}$$

There exists a  $T_1$ -compatible walk between  $w$  and every vertex of the graph.

There exists no  $T_1$ -compatible walk between  $x$  and  $u$  or  $y$ .



$$T_1 = \{uvy, wvy\}$$

$$T_2 = \{uvy, wvy, uvx\}$$

There exists a  $T_1$ -compatible walk between  $w$  and every vertex of the graph.

There exists no  $T_1$ -compatible walk between  $x$  and  $u$  or  $y$ .

The set  $T_2$  is a **connecting transition set** of the graph.



# Minimum connecting transition set

## Minimum connecting transition set

Smallest set  $T$  such that a graph  $G$  is  $T$ -connected.  
(similar to minimum spanning trees)

Several papers study robustness of graph properties to malfunctioning transitions.

→ Application of minimum connecting transition sets to robust network design ?

## 1 Context

## 2 Our results

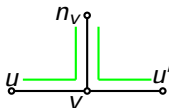
- Upper bounds
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- Main results

# General case

Pick a neighbour  $n_v$  for every vertex  $v$ .

$$T = \bigcup_{v \in V} \bigcup_{u \in N(v) \setminus \{n_v\}} \{uvn_v\} \text{ is connecting.}$$

$$|T| = 2|E| - |V|$$



If  $G$  is a tree,  $|T| = n - 2$  and this construction is optimal !

## General upper bound

A minimum connecting transition set of a graph of  $n$  vertices has size at most  $n - 2$ .

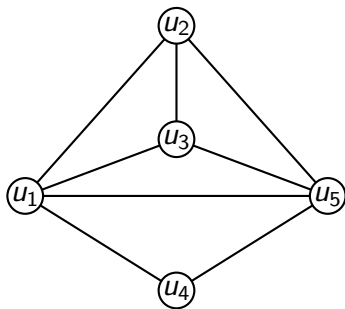
# Lower bounds and reachable values

Complete graph : minimum connecting transition set of size 0.

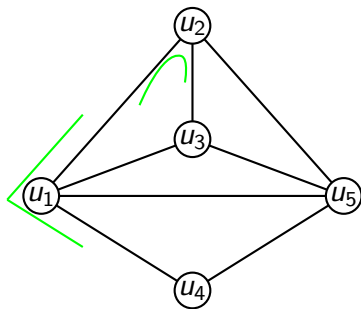
Every value  $k$  between 0 and  $n - 2$  is reachable : start from a tree of size  $k + 2$  and add  $n - k + 2$  dominating vertices.

## Question

Is the size of a minimum connecting transition set  $k - 2$  where  $k$  is the number of non-dominating vertices ?

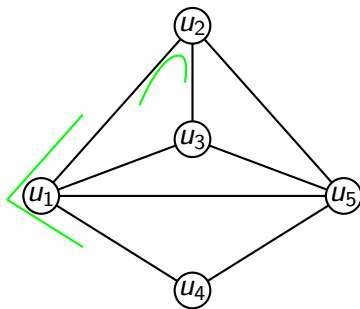


3 non-dominating vertices.

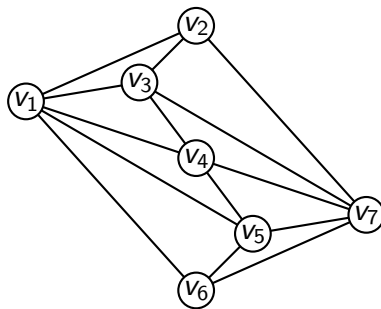


3 non-dominating vertices.

Size of MCTS : 2.

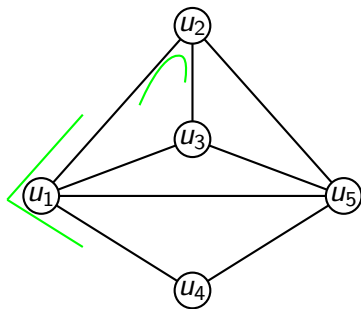


3 non-dominating vertices.  
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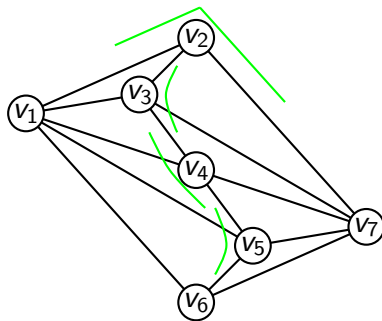


7 non-dominating vertices.

## Upper bounds



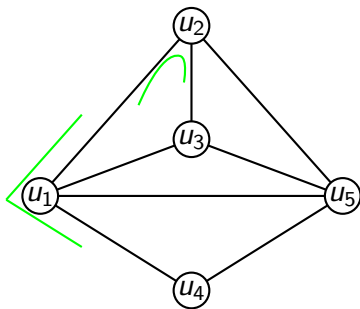
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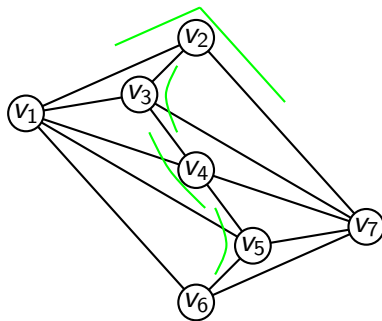
7 non-dominating vertices.  
Size of MCTS : 4.



## Upper bounds



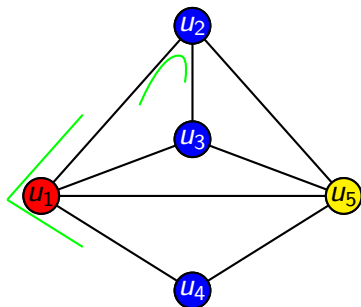
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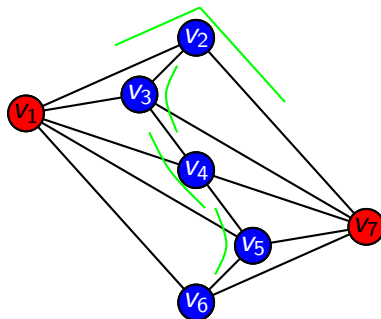
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### Key

Look at the connected components of the complementary graph ! (co-cc)



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Size of MCTS : 2.



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## Key

Look at the connected components of the complementary graph ! (co-cc)

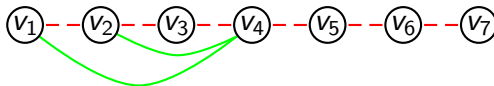
# Improved upper bound

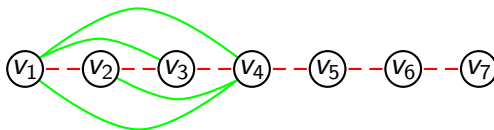
## Theorem

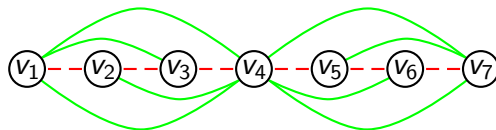
Every connected graph  $G$  has a connecting transition set of size  $\tau(G)$  where

$$\tau(G) = \sum_{\substack{C \text{ co-cc of } G \\ |C| \geq 2}} \begin{cases} |C| - 2 & \text{if } G[C] \text{ is connected} \\ |C| - 1 & \text{otherwise} \end{cases}$$

$\text{Co-}P_7$ 

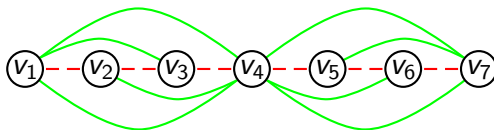
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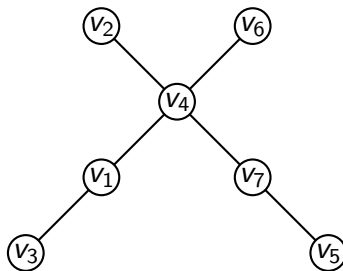
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Connecting transition set of size 4 but  $\tau(\overline{P_7}) = 5$ .

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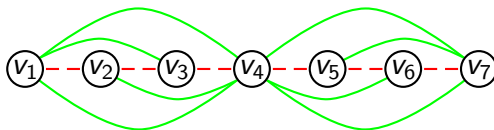


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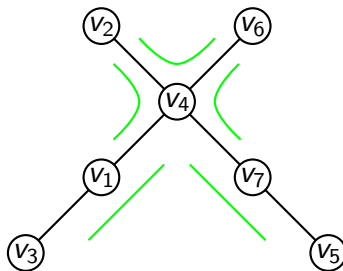




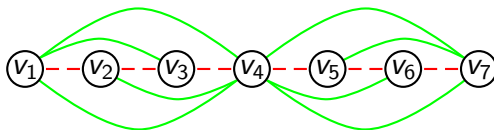
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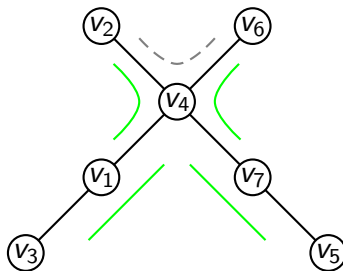
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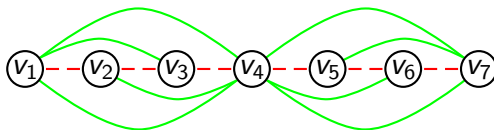
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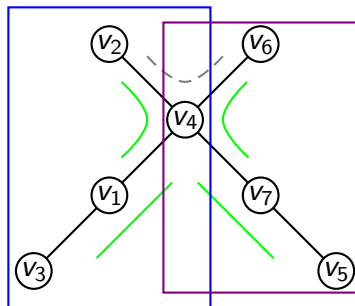
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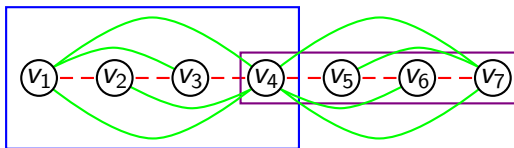


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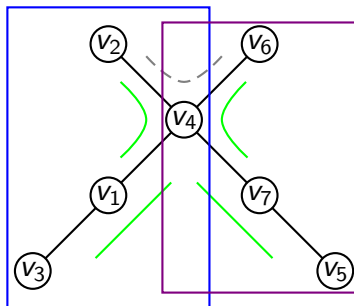


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# Optimal connecting hypergraph

## Connecting hypergraph :

A *connecting hypergraph* of a connected graph  $G$  is a set  $H$  of subsets of  $V(G)$  called *connecting hyperedges*, such that

- For all  $e \in H$ ,  $|e| \geq 2$ .
- For all  $e \in H$ ,  $G[e]$  is connected.
- For all  $uv \notin E(G)$ , there exists  $e \in H$  such that  $u, v \in e$

$$\text{cost}(H) = \sum_{e \in H} (|e| - 2)$$

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$$\text{cost}(H) = \sum_{e \in H} (|e| - 2)$$

Finding a **minimum connecting transition set** is equivalent to finding **connecting hypergraph of minimum cost** !

# Complexity and approximation

## Complexity

Finding a minimum connecting transition set of a graph is NP-complete.

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Finding a minimum connecting transition set of a graph is NP-complete.

## Approximation

The size of a minimum connecting transition of a graph  $G$  is at least  $\frac{2}{3}\tau(G)$  (tight bound) where

$$\tau(G) = \sum_{\substack{C \text{ co-cc of } G \\ |C| \geq 2}} \begin{cases} |C| - 2 & \text{if } G[C] \text{ is connected} \\ |C| - 1 & \text{otherwise} \end{cases}$$

→ We have a  $O(|V|^2)$   $\frac{3}{2}$ -approximation !



# Our results

- Bounds or exact results for several families of graphs (trees, graphs with cut-vertices).
- Reformulation of the problem.
- Polynomial  $\frac{3}{2}$ -approximation.
- Proof of NP-completeness (even when restricted to co-planar graphs).

# Future works

- Sparse graphs (bounded treewidth ? bounded maximum average degree ? planar ?).
- Stretch of the minimum connecting sets.
- Starting with forbidden transitions.
- Directed graphs.

Thank you !